Chapter 9:

A New Optimal Orthogonal Additive Randomized **Response Model Based on Moments Ratios of Scrambling Variable**

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Additional information is available at the end of the chapter

Introduction

The Randomized response (RR) technique was first presented by Warner (1965) mainly to cut down the probability of (i) reduced response rate and (ii) inflated response bias experienced in direct or open survey relating to sensitive issues. Some recent involvement to randomized response sampling is given by Fox and Tracy (1986), Singh and Mathur (2004, 2005), Gjestvang and Singh (2006), Singh and Tarray (2013, 2014, 2015, 2016) and Tarray and Singh (2016, 2017, 2018). We below give the description of the model due to Singh (2010):

Singh (2010) Additive Model

Let there be k scrambling variables denoted by S_j , j = 1, 2, ..., k whose mean θ_j (i.e. $E(S_j) = \theta_j$) and variance γ_i^2 (i.e. V(S_i) = γ_i^2) are known. In Singh's (2010) proposed optimal new orthogonal additive model named as (POONAM), each respondent selected in the sample is requested to rotate a spinner, as shown in Fig. 9.1, in which the proportion of the k shaded areas, say P1, P2, ... Pk are orthogonal to the means of the k scrambling variables, say $\theta_1, \theta_2, \dots, \theta_k$ such that:

$$\sum_{j=1}^{k} \mathbf{P}_{j} \mathbf{\Theta}_{j} = \mathbf{0} \tag{9.1}$$





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Figure 9.1: Spinner for POONAM (Singh (2010))

Now if the pointer stops in the j^{th} shaded area, then the i^{th} respondent with real value of the sensitive variable, say Y_{i} , is requested report the scrambled response Z_{i} as:

$$\mathbf{Z}_{i} = \mathbf{Y}_{i} + \mathbf{S}_{i} \tag{9.3}$$

Assuming that the sample of size n is drawn from the population using simple random sampling with replacement (SRSWR). Singh (2010) suggested an unbiased estimator of the population mean μ_{Y} as

$$\hat{\mu}_{Y} = \frac{1}{n} \sum_{j=1}^{n} Z_{j}$$
(9.4)

The variance of $\hat{\mu}_{Y}$ is given by

$$V(\hat{\mu}_{Y}) = \frac{1}{n} \left[\sigma_{y}^{2} + \sum_{j=1}^{k} P_{j}(\theta_{j}^{2} + \gamma_{j}^{2}) \right]$$
(9.5)

The proposed procedure

It is to be noted that the mean θ_j and variance γ_j^2 of the jth scrambling variable S_j (j=1,2,...,k) are known. Author has to propose a new additive model based on standardized scrambling

variable
$$\mathbf{S}_{j}^{*} = \left(\frac{\mathbf{S}_{j}^{2}}{\theta_{j}(1+\mathbf{C}_{j}^{2})}\right), j = 1, 2, \dots, k$$
.

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As demonstrated in Fig. 9.2, in which the proportion of the k shaded areas, say $P_1, P_2, ..., P_k$ are orthogonal to the means of the k scrambling variables $(S_j^*, \forall j = 1, 2, ..., k)$, say $\theta_1, \theta_2, ..., \theta_k$ such that:

$$\sum_{j=1}^{k} P_j \theta_j = 0 \tag{9.6}$$

and
$$\sum_{j=1}^{k} P_j = 1$$
 (9.7)

Now if the pointer stops in the jth shaded area, then the ith respondent with real value of the sensitive variable, say Y_i , is requested report the scrambled response Z_i^* as:

$$Z_i^* = Y_i + S_j^*$$
(9.8)

we prove the following theorems.



Figure 9.2: Spinner for proposed procedure.

Bayesian Analysis and Reliability Estimation of Generalized Probability Distributions

Theorem 9.1

$$\hat{\mu}_{ST} = \frac{1}{n} \sum_{i=1}^{n} Z_i^*$$
(9.9)

Proof

Let E_1 and E_2 denote the expectations, then we have

$$\begin{split} E(\hat{\mu}_{ST}) &= E_1 E_2 \left[\frac{1}{n} \sum_{i=1}^n Z_i^* \right] \\ &= E_1 \left[\frac{1}{n} \sum_{i=1}^n E_2(Z_i^*) \right] \\ &= E_1 \left[\frac{1}{n} \sum_{i=1}^n \left\{ Y_i \sum_{j=1}^k P_j + \sum_{j=1}^k P_j E_2(S_j^*) \right\} \right] \\ &= E_1 \left[\frac{1}{n} \sum_{j=1}^n Y_i \right] = \mu_Y \quad \text{, since } \sum_{j=1}^k P_j = 1 \text{ and } E_2(S_j^*) = \theta_j, \end{split}$$

which proves the theorem.

Theorem 9.2

$$V(\hat{\mu}_{ST}) = \frac{1}{n} \left[\sigma_{y}^{2} + \sum_{j=1}^{k} \frac{P_{j}A_{j}}{(1+C_{j}^{2})^{2}} \right]$$
(9.10)

where

$$A_{j} = \left[\beta_{2}(S_{j})C_{j}^{4} + 4C_{j}^{3}G_{1}(S_{j}) + 6C_{j}^{2} + 1\right],$$

$$\beta_{2}(S_{j}) = \frac{\mu_{4}(S_{j})}{\gamma_{j}^{4}}, G_{1}(S_{j}) = \frac{\mu_{3}(S_{j})}{\gamma_{j}^{3}} \text{ is the Fisher 's measure of skewness , } \mu_{3}(S_{j})$$

and $\mu_4(S_j)$ are third and fourth central moments of the scrambling variable $S_j.$

Proof

$$V(\hat{\mu}_{Y}) = E_{1}V_{2}(\hat{\mu}_{Y}) + V_{1}E_{2}(\hat{\mu}_{Y})$$

= $E_{1}\left[V_{2}\left(\frac{1}{n}\sum_{i=1}^{n}Z_{i}^{*}\right)\right] + V_{1}\left[E_{2}\left(\frac{1}{n}\sum_{i=1}^{n}Z_{i}^{*}\right)\right]$
= $E_{1}\left[\frac{1}{n^{2}}\sum_{i=1}^{n}V_{2}(Z_{i}^{*})\right] + V_{1}\left[\frac{1}{n}\sum_{i=1}^{n}E_{2}(Z_{i}^{*})\right]$

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$$= \frac{1}{n} \sum_{j=1}^{k} \frac{P_{j}A_{j}}{(1+C_{j}^{2})^{2}} + \frac{\sigma_{y}^{2}}{n}$$
$$= \frac{1}{n} \left[\sigma_{y}^{2} + \sum_{j=1}^{k} \frac{P_{j}A_{j}}{(1+C_{j}^{2})^{2}} \right]$$

Note that:

$$\begin{split} V_{2}(Z_{i}^{*}) &= E_{2}\left(Z_{i}^{*2}\right) - \left(E_{2}\left(Z_{i}^{*}\right)\right)^{2} \\ E_{2}(Z_{i}^{*2}) &= E_{2}\left(Y_{i} + S_{j}^{*}\right)^{2} = E_{2}\left[Y_{i}^{2} + S_{j}^{*2} + 2Y_{i}S_{j}^{*}\right] \\ &= Y_{i}^{2}\sum_{j=1}^{k}P_{j} + \sum_{j=1}^{k}P_{j}E_{2}(S_{j}^{*2}) + 2Y_{i}\sum_{j=1}^{k}P_{j}E_{2}(S_{j}^{*}) \\ &= Y_{i}^{2} + \sum_{j=1}^{k}P_{j}E_{2}(S_{j}^{*2}) + 2Y_{i}\sum_{j=1}^{k}P_{j}\theta_{j} \\ &= Y_{i}^{2} + \sum_{j=1}^{k}P_{j}E_{2}(S_{j}^{*2}), \\ \text{Since} \quad \sum_{j=1}^{k}P_{j}\theta_{j} = 0, \\ \text{and} \quad E_{2}(S_{j}^{*2}) &= E_{2}\left\{\frac{S_{j}^{4}}{\theta_{j}^{2}(1+C_{j}^{2})^{2}}\right\} \\ &= \frac{1}{\theta_{j}^{2}(1+C_{j}^{2})^{2}}E_{2}(S_{j}^{4}) \\ &= \frac{1}{\theta_{j}^{2}(1+C_{j}^{2})^{2}}E_{2}\left\{(S_{j}-\theta_{j})^{4} + 6\theta_{j}^{2}(S_{j}-\theta_{j})^{2} + 4\theta_{j}(S_{j}-\theta_{j})^{3} + 4\theta_{j}^{2}(S_{j}-\theta_{j})\right\} \end{split}$$

$$= \frac{1}{\theta_{j}^{2} (1 + C_{j}^{2})^{2}} \left\{ \mu_{4}(S_{j}) + 4\theta_{j} \mu_{3}(S_{j}) + 6\theta_{j}^{2} \gamma_{j}^{2} + \theta_{j}^{4} \right\}$$

Bayesian Analysis and Reliability Estimation of Generalized Probability Distributions

$$\begin{split} &= \mu_4(S_j) + 4\theta_j \mu_3(S_j) + 6\theta_j^2 \gamma_j^2 + \theta_j^4 \\ &= \frac{\theta_j^4 A_j}{\theta_j^2 (1 + C_j^2)^2} = \frac{\theta_j^2 A_j}{(1 + C_j^2)^2} \\ &\text{Thus } E_2(Z_i^{*2}) = Y_i^2 + \sum_{j=1}^k \frac{P_j A_j}{(1 + C_j^2)^2} \\ &\text{Therefore } V_2(Z_i^*) = Y_i^2 + \sum_{j=1}^k \frac{P_j A_j}{(1 + C_j^2)^2} - Y_i^2 \end{split}$$

$$= \sum_{j=1}^{k} \frac{P_{j}A_{j}}{(1+C_{j}^{2})^{2}}$$

Efficiency Comparison

From (9.5) and (9.4), we have

$$V(\hat{\mu}_{ST}) < V(\hat{\mu}_{Y}) \text{ if}$$

i.e. if $\frac{1}{n} \left[\sigma_{y}^{2} + \sum_{j=1}^{k} \frac{P_{j}A_{j}}{(1+C_{j}^{2})^{2}} \right] < \frac{1}{n} \left[\sigma_{y}^{2} + \sum_{j=1}^{k} P_{j}\theta_{j}^{2}(1+C_{j}^{2}) \right]$
i.e. if $\sum_{j=1}^{k} \frac{P_{j}A_{j}}{(1+C_{j}^{2})^{2}} < \sum_{j=1}^{k} P_{j}\theta_{j}^{2}(1+C_{j}^{2})$
i.e. if $\sum_{j=1}^{k} P_{j} \left[\frac{A_{j}}{(1+C_{j}^{2})^{2}} - \theta_{j}^{2}(1+C_{j}^{2}) \right] < 0$
i.e. if $\frac{A_{j}}{(1+C_{j}^{2})^{2}} < \theta_{j}^{2}(1+C_{j}^{2}) \quad \forall j = 1,2,...,k,$
i.e. if $A_{j} < \theta_{j}^{2}(1+C_{j}^{2})^{3} \quad \forall j = 1,2,...,k,$
i.e. if $\theta_{j}^{2} > \frac{A_{j}^{2}}{(1+C_{j}^{2})^{3}} \quad \forall j = 1,2,...,k.$ (9.11)

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In case the scrambling variable S_j follows a normal distribution

(i.e. $\mathrm{S}_{j}\sim\!\!\mathrm{N}(\theta_{j}\,,\,\gamma_{j}^{2})\,,\quad j=1,2,...,k$) , then A_{j} reduces to:

$$A_{j}^{*} = \left\{ 1 + 3C_{j}^{2}(2 + C_{j}^{2}) \right\}$$
(9.12)

Thus the condition (9.1) reduces to:

$$\theta_{j}^{2} > \frac{(1+6C_{j}^{2}+3C_{j}^{4})}{(1+C_{j}^{2})^{3}}$$
(9.13)

The condition (9.3) clearly indicates that $\left\{\theta_j^2 > \frac{(1+6C_j^2+3C_j^4)}{(1+C_j^2)^3}, \forall j = 1, 2, ..., k\right\}$ then the

proposed model is always better.

Further, suppose $S_j \sim N(\theta_j, \gamma_j^2)$, $\forall j = 1, 2, ..., k$, $\theta = 0$ and $\theta_j = 0 \forall j = 1, 2, ..., k$, then the variance expression in (9.5) and (9.4) respectively reduce to:

$$\mathbf{V}(\hat{\boldsymbol{\mu}}_{\mathbf{Y}}) = \frac{1}{n} \left[\boldsymbol{\sigma}_{\mathbf{y}}^{2} + \sum_{j=1}^{k} \mathbf{P}_{j} \boldsymbol{\gamma}_{j}^{2} \right]$$
(9.14)

and

$$\mathbf{V}(\hat{\boldsymbol{\mu}}_{\mathrm{ST}}) = \frac{1}{n} \left[\boldsymbol{\sigma}_{\mathrm{y}}^2 + 3 \right] \tag{9.15}$$

From (9.4) and (9.5) we have

$$V(\hat{\mu}_{ST}) - V(\hat{\mu}_{Y}) = \frac{1}{n} \left(\sum_{j=1}^{k} P_{j} \gamma_{j}^{2} - 3 \right)$$
$$= \frac{1}{n} \sum_{j=1}^{k} P_{j} \left(\gamma_{j}^{2} - 3 \right)$$
(9.16)

which is always positive if

$$(\gamma_{j}^{2} - 3) > 0 \qquad \forall j = 1, 2, ..., k$$

i.e. if $\gamma_{j}^{2} > 3 \qquad \forall j = 1, 2, ..., k$ (9.17)

Thus when $S_j \sim N(0, \gamma_j^2)$, $\forall j = 1, 2, ..., k$, $\hat{\mu}_{ST}$ is more efficient as long as the condition (9.7) is satisfied.

Bayesian Analysis and Reliability Estimation of Generalized Probability Distributions

In case S_j follows a normal distribution (i.e. S_j ~N(θ_j , γ_j^2), $\forall j = 1, 2, ..., k$), PRE of $\hat{\mu}_{ST}$ with $\hat{\mu}_Y$ by using the formula:

$$PRE(\hat{\mu}_{ST}, \hat{\mu}_{Y}) = \frac{\left[\sigma_{y}^{2} + \sum_{j=1}^{k} P_{j} \left\{ (\theta_{j}^{2} + \gamma_{j}^{2}) \right\} \right]}{\left[\sigma_{y}^{2} + \sum_{j=1}^{k} \frac{P_{j} A_{j}^{*}}{(1 + C_{j}^{2})^{2}} \right]} \times 100$$
(9.18)

where A_j^* is given in (9.2).

Suppose $\gamma = 40$, $\gamma_1 = 30$, $\gamma_2 = 40$, $\gamma_3 = 20$, $\gamma_4 = 10$, $P_1 = 0.02$, $P_2 = 0.05$, $P_3 = 0.06$, $P_4 = 0.87$ with k = 4. σ_y^2 , θ_1 , θ_2 , θ_3 and θ_4 as listed in Table 9.1.

σ_Y^2	θ_1	θ_2	θ_3	θ_4	PRE
	300	200	100	-25.20	18523.16
	800	700	600	-100.00	242264.29
	1300	1200	1100	-174.70	732808.85
25	1800	1700	1600	-249.40	1490172.55
	300	200	100	-25.20	4130.07
	800	700	600	-100.00	53073.44
	1300	1200	1100	-174.70	160380.06
125	1800	1700	1600	-249.40	326053.37
	300	200	100	-25.20	2362.49
	800	700	600	-100.00	29839.47
	1300	1200	1100	-174.70	90081.79
225	1800	1700	1600	-249.40	183091.37
	300	200	100	-25.20	1672.71
325	800	700	600	-100.00	20772.56

Table 9.1: $PRE(\hat{\mu}_{ST}, \hat{\mu}_{Y})$

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	1300	1200	1100	-174.70	62648.32	
	1800	1700	1600	-249.40	127301.32	
	300	200	100	-25.20	1305.25	
	800	700	600	-100.00	15942.52	
	1300	1200	1100	-174.70	48034.22	
425	1800	1700	1600	-249.40	97581.38	
	300	200	100	-25.20	1076.99	
	800	700	600	-100.00	12942.05	
	1300	1200	1100	-174.70	38955.77	
525	1800	1700	1600	-249.40	79119.00	
	300 200 100		-25.20	921.41		
	800	700	600	-100.00	10897.13	
	1300	1200	1100	-174.70	32768.55	
625	1800	1700	1600	-249.40	66536.36	
	300	200	100	-25.20	808.58	
	800	700	600	-100.00	9414.01	
	1300	1200	1100	-174.70	28281.11	
725	1800	1700	1600	-249.40	57410.48	
	300	200	100	-25.20	723.01	
	800	700	600	-100.00	8289.13	
	1300	1200	1100	-174.70	24877.59	
825	1800	1700	1600	-249.40	50488.93	

Chapter 9: A New Optimal Orthogonal Additive Randomized Response Model Based on Moments Ratios of Scrambling Variable

Bayesian Analysis and Reliability Estimation of Generalized Probability Distributions

From Table 9.1 $PRE(\hat{\mu}_{ST}, \hat{\mu}_Y)$ are greater than 100. It shows $\hat{\mu}_{ST}$ is more efficient than $\hat{\mu}_Y$ with substantial gain. Thus, the estimator $\hat{\mu}_{ST}$ over $\hat{\mu}_Y$ is recommended.

σ_y^2	25	125	225	325	425	525	625	725	825
PRE	835.71	260.94	190.35	162.80	148.13	139.02	132.80	128.30	124.88

Table 9.2: *PRE of* $\hat{\mu}_{ST}$ *ove* $\hat{\mu}_{Y}$.

The minimum values from 9.2 is observed as 124.88 and maximum 835.71 with a median of 148.13.

Table 9.2 PRE remains higher if the value of σ_y^2 is small. In that case the value of σ_y^2 will be around 0.5 to 5.0 (see Singh (2010), p. 67). It is observed that the PRE value decreases from 5985.71 to 2675.00 as the value of σ_y^2 increases from 0.5 to 5.0.

Case k = 2 and the PRE($\hat{\mu}_{ST}$, $\hat{\mu}_{Y}$) for different parameters. Results are shown in Table 9.3. Thus, the estimator $\hat{\mu}_{ST}$ over the estimator $\hat{\mu}_{Y}$ is recommended.

P ₁	θ_1	θ_2	σ_Y^2	PRE
			25	1514232.14
			125	331316.41
			225	186046.05
			325	129355.18
			425	99155.37
			525	80394.89
			625	67609.08
			725	58335.85
0.2	1300	-325.0	825	51302.54
			25	219089.29
			125	48003.91
			225	26993.42
			325	18794.21
0.4	300	-200.0	425	14426.40

Table 9.3: *PRE of the estimator* $\hat{\mu}_{ST}$ *over the estimator* $\hat{\mu}_{Y}$ *with* k = 2.

			525	11713.07
			625	9863.85
			725	8522.66
			825	7505.43
			25	1528536.91
			125	334445.57
			225	187802.78
			325	130576.32
			425	100091.20
			525	81153.47
			625	68246.87
			725	58886.03
0.4	800	-533.3	825	51786.27
			25	1289517.86
			125	282160.16
			225	158449.56
			325	110172.26
			425	84454.44
			525	68478.22
			625	57589.97
			725	49692.99
0.8	300	-1200.0	825	43703.50

Conclusion

This paper elucidates amelioration over the Singh's (2010) randomized response model. We have advocated the optimal orthogonal additive randomized response model. The proposed model is found to be more resourceful both theoretically as well as numerically than the additive randomized response model studied by Singh (2010). Thus, the suggested RR procedure is therefore indorsed for its use in practice as an alternative to Singh's (2010) model.

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Bayesian Analysis and Reliability Estimation of Generalized Probability Distributions

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